

Original system
 $A\vec{x} = \vec{b}$

$$\begin{bmatrix} 1 & 2 & 1 \\ 4 & 5 & 10 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 10 \end{bmatrix}$$

Solutions are: $\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 5 \\ 0 \\ -1 \end{bmatrix}$, $\begin{bmatrix} -5 \\ 4 \\ 1 \end{bmatrix}$, ...

BFS Basic non-feasible solution non-basic non-feasible solution

Consider

$$\left[\begin{array}{ccc|cc} 1 & 2 & 1 & 1 & 0 \\ 4 & 5 & 10 & 0 & 1 \end{array} \right] \begin{bmatrix} x \\ y \\ z \\ \vec{x}_a \\ \vec{x}_b \end{bmatrix} = \begin{bmatrix} 4 \\ 10 \end{bmatrix}$$

artificial variables

augmented system
 $[A|I] \begin{bmatrix} \vec{x} \\ \vec{x}_a \end{bmatrix} = \vec{b}$

Solutions are $\begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 5 \\ 0 \\ -1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} -5 \\ 4 \\ 1 \\ 0 \\ 0 \end{bmatrix}$,

BFS B nF S nB nF S

$$\Leftrightarrow A\vec{x} + I\vec{x}_a = \vec{b}$$

of original problem ($A\vec{x} = \vec{b}$)

and $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 4 \\ 10 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 1 \\ 3 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 3 \\ 6 \end{bmatrix}$

BFS BFS nB F S

of augmented problem $[A|I] \begin{bmatrix} \vec{x} \\ \vec{x}_a \end{bmatrix} = \vec{b}$
 but NOT original problem $A\vec{x} = \vec{b}$

" $[A|I] \begin{bmatrix} \vec{x} \\ \vec{x}_a \end{bmatrix} = \vec{b} \Rightarrow A\vec{x} = \vec{b}$ " if $\vec{x}_a = \vec{0}$

"How to do this?"
 ??
 ↓

Augmented solution is solution to original problem if all artificial variables $\equiv 0$

Eg 3.4

$$x_0 = x_1 + x_2$$

$$\begin{cases} 2x_1 + x_2 \geq 4 \\ x_1 + 2x_2 = 6 \\ x_1, x_2 \geq 0 \end{cases}$$

Not in FCF

⇒ Standard form

$$x_0 = x_1 + x_2 - 0x_3$$

$$\begin{cases} 2x_1 + x_2 - x_3 = 4 \\ x_1 + 2x_2 = 6 \\ x_1, x_2, x_3 \geq 0 \end{cases} \quad A = \begin{pmatrix} 2 & 1 & -3 \\ 1 & 2 & 0 \end{pmatrix}$$

Try $B = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$

$$\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{2}{3} \\ \frac{8}{3} \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{2}{3} \\ \frac{8}{3} \\ 0 \end{pmatrix} \text{ a BFS}$$

Try $B = \begin{pmatrix} 1 & -3 \\ 2 & 0 \end{pmatrix}$

$$\begin{pmatrix} 1 & -3 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3 \\ -\frac{1}{3} \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \\ -\frac{1}{3} \end{pmatrix} \text{ Basic solution but not feasible}$$

M-method: artificially create an identity matrix

$$x_0 = x_1 + x_2 - 0x_3 - Mx_4 - Mx_5$$

$$\begin{cases} 2x_1 + x_2 - x_3 + x_4 = 4 \\ x_1 + 2x_2 + x_5 = 6 \\ x_1, x_2, x_3, x_4, x_5 \geq 0 \end{cases} \quad \text{new } A = \begin{pmatrix} 2 & 1 & -3 & 1 & 0 \\ 1 & 2 & 0 & 0 & 1 \end{pmatrix}$$

(i) obviously $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 4 \\ 6 \end{pmatrix}$

is a starting BFS for the augmented artificial problem, but not of the original problem

(ii) the cost $-M$ will drive x_4 & x_5 to zero so that at optimum

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} * \\ * \\ * \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} * \\ * \\ * \end{pmatrix} \text{ is the optimal solution of the original problem}$$